# Clustering in Cell Cycle Dynamics with General Forms of Feedback

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# Acknowledgments

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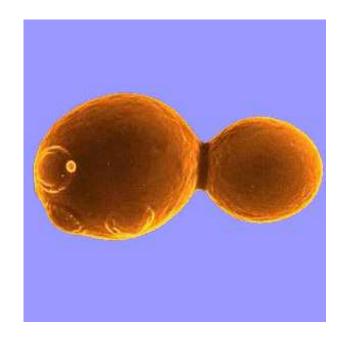
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#### Saccharomyces cerevisiae





Photos: Wikipedia, www.kaeberleinlab.org, www.alltech.com

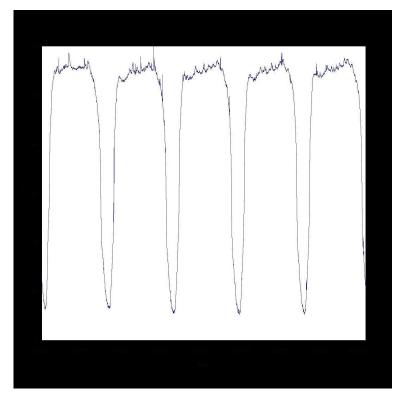
Brewer's, Baker's or Ale Yeast.

Studied by biologists as a model eukaryotic organism.

Yeast are used in many bio-engineering processes.

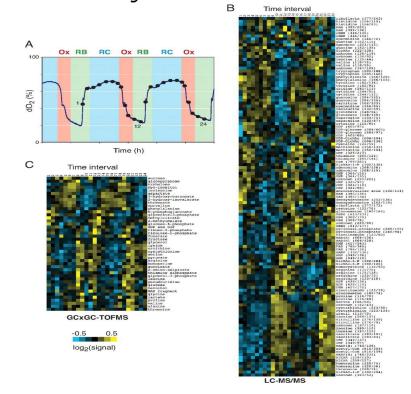
# Metabolic Oxygen Oscillations

# Disolved $O_2$ vs. time:



20 hrs. Range 5% - 65%.

## Microarray time-series:



Z.Chen et. al. *Science* **316** (2007).

#### Oxygen Oscillations

Oscillations occur under the following conditions:

- Well-mixed bioreactor.
- Slow input and output.
- Highly oxygenated media
- High cell density.
- Boczko observed: The period of oscillation is always nearly an integer fraction of the culture's doubling time.

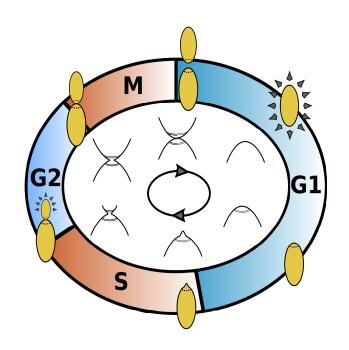
#### **Cell Cycle of Budding Yeast**

G1: growth phase, begins with cell division

S: replication phase, begins with budding

G2: second growth phase

M: narrowing or "necking", ends in cell division



Cell cycle synchrony is impossible to sustain in the lab. Initially synchronized cultures quickly de-synch.

A casual link between  $O_2$  oscillations and the cell cycle was dismissed in one early paper without data.

#### Clustering

By *Cluster* we mean a group of cells traversing the cell cycle in near synchrony. (Not spatial clustering.)

#### **Hypotheses:**

A large cluster of cells in one part of the cell cycle might influence the progress of cells in another part (thru metabolic products?).

This feedback might reinforce the formation/stability of clusters.

Clustering and Oscillations are intrinsically linked.

#### Model of RS Feedback

 $x_i(t) \in [0,1]$  - state of *i*-th cell,  $x_i = 1 \mapsto x_i = 0$  (division).

Signaling region S = [0, s). Responsive region R = [r, 1).

 $\sigma = \#\{\text{cells in } S\}/n.$ 

RS feedback model:

$$\frac{dx_i}{dt} = \begin{cases} 1, & \text{if } x_i \notin R\\ 1 + \rho(\sigma), & \text{if } x_i \in R. \end{cases}$$
 (1)

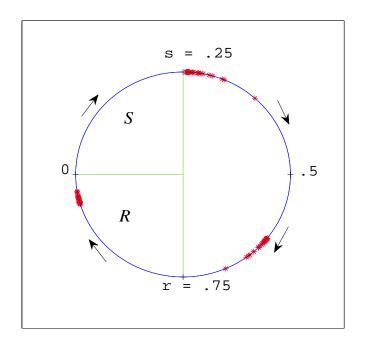
 $\rho(\sigma)$  is a "response" function. Assume +/- monotone.

**Proposition.** Synchronized solution is stable for positive feedback, unstable for negative.

#### **Clusters Exist - Simulations**

 ${\cal S}$  - Signaling,  ${\cal R}$  - Responsive Simulation, 500 cells,

Negative feedback & noise:



 Simulations with RS feedback almost always form clusters.

 Analysis of simple RS feedback confirms clustering is robust.

 We began looking for clustering in yeast experiments.

#### **Clusters Exist - Mathematics**

n - number of cells,  $n \sim O(10^{10})$ . Phase space is  $\mathbb{T}^n$ .

In the model (1), a synchronized cluster of cells will persist, so we may reduce the dimension to k, the number of clusters.

A clustered solution  $\{x_i(t)\}_{i=1}^k$  is *cyclic* if  $\exists$  a time d > 0 s.t.:

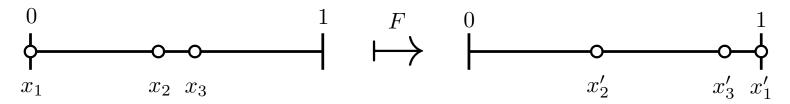
$$x_i(d) = x_{i+1}(0) \quad \forall \quad i = 1, \dots, k-1,$$
  
and  $x_k(d) = x_1(0) \mod 1.$ 

**Theorem.** If k is a divisor of n, then a cyclic k cluster solution exists consisting of n/k cells in each cluster.

Special Cases: k = 1 - synchronized. k = n - uniform.

#### **Cluster Systems**

Strategy: Study solutions consisting of k clusters. Use the map F below.  $F^k$  is the Poincaré return map.

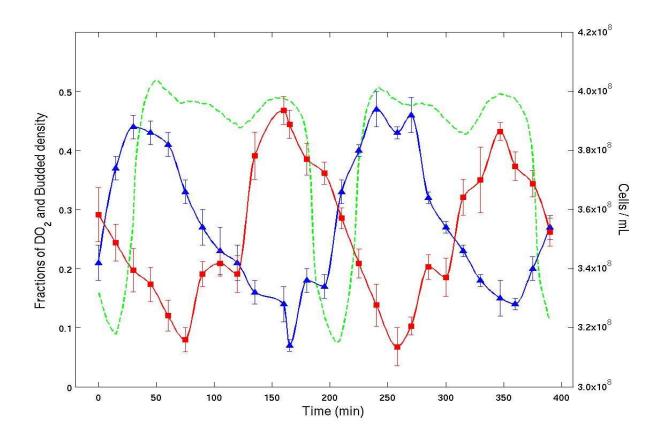


F consists of flowing until  $x_k(t)=1$ , then reordering indices.  $F:S\to S,\ S=\{0\le x_2\le \ldots \le x_k\le 1\}.$ 

Proof: F permutes the boundary of S + Brouwer  $\Rightarrow$  F has interior fixed point  $\iff$  k-cyclic solution.

We can also use F to study solutions for small k in detail.

#### **Clusters Exist - Experiments**



Oxygen dilution (green), bud index (blue) and cell density (red) over one cell cycle period. There are 2 clusters.

#### Isolated Clusters and the Geometric Constant M

If the distance between two clusters is more that |R| + |S| then those two clusters will not interact.

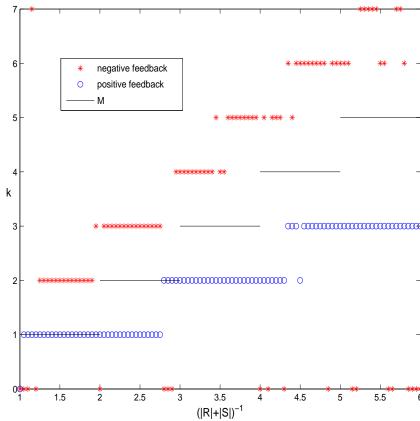
$$M = \lfloor (|R| + |S|)^{-1} \rfloor.$$

- max # of clusters that can exist without interactions.

Solutions with  $k \leq M$  noninteracting clusters will be periodic.

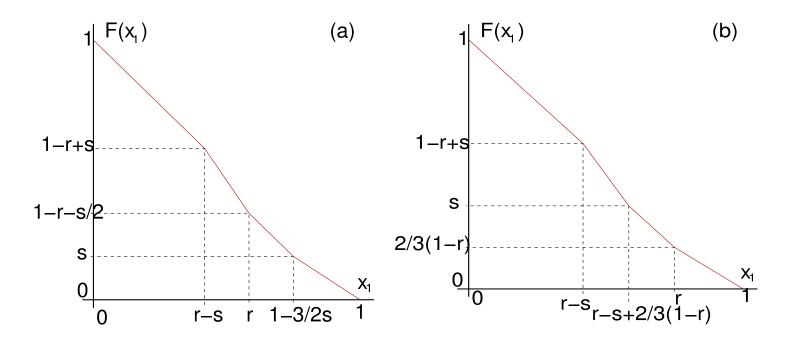
Theorem - For positive feedback (1) the set of solutions with non-interacting clusters is locally asymptotically stable. For negative feedback it is unstable.

## Negative vs. Positive Feedback



The number of clusters that form in simulations compared with  $M = \lfloor (|R| + |S|)^{-1} \rfloor$ .

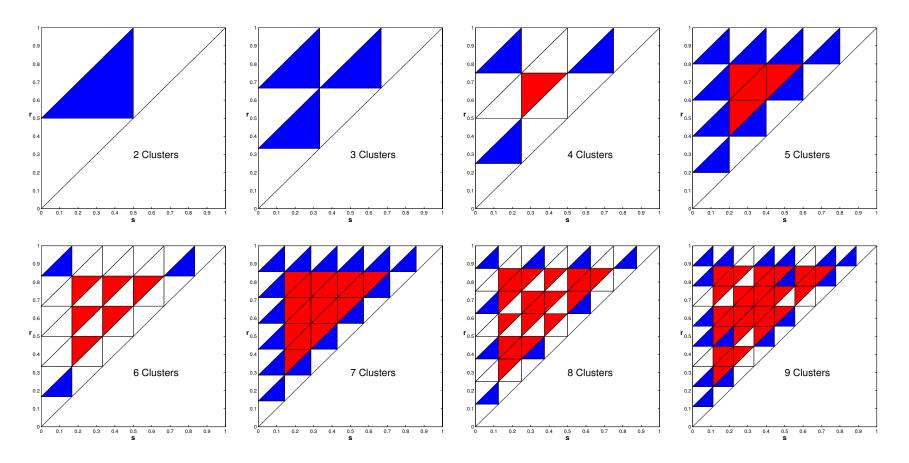
### 2 Cluster Systems - Detailed Analysis



F for positive feedback, k=2. (a)  $r+\frac{3}{2}s<1$ . (b)  $r+\frac{3}{2}s\geq1$ .

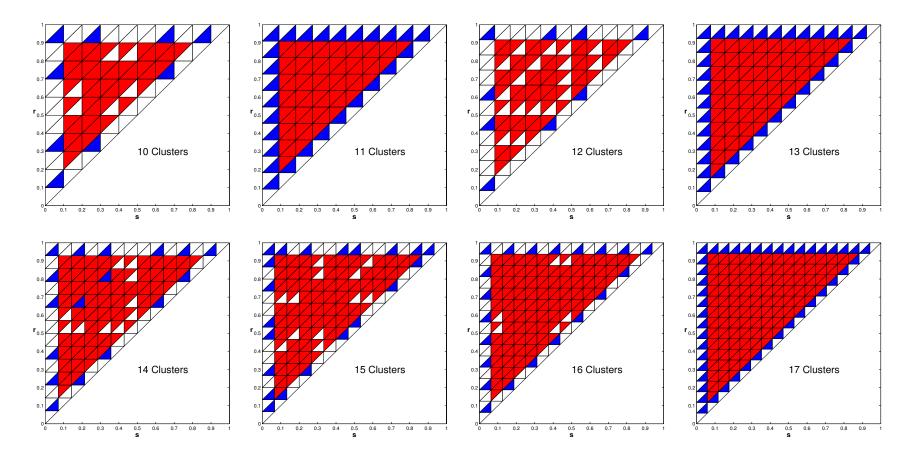
From F we can infer all dynamics.

#### Stability of k-cyclic solution in r-s space - Neg. Feedback



 $k=2,\ldots,9.$  In subtriangles the "order of events" is invariant. Blue - Stable, White - Neutral, Red - Unstable.

# Stability of k-cyclic solutions in r-s parameter space



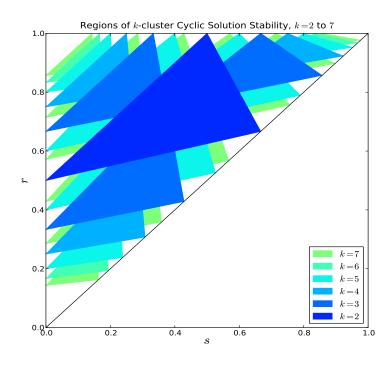
k = 10, ..., 17Primes are Regular, Composites are Irregular!!.

Ohio University - Since 1804

Department of Mathematics

## Clustering is Universal for Negative Feedback

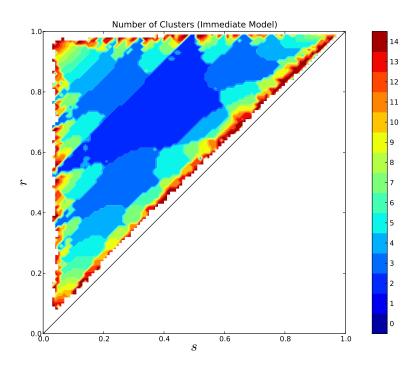
### Overlay of Stable Regions:



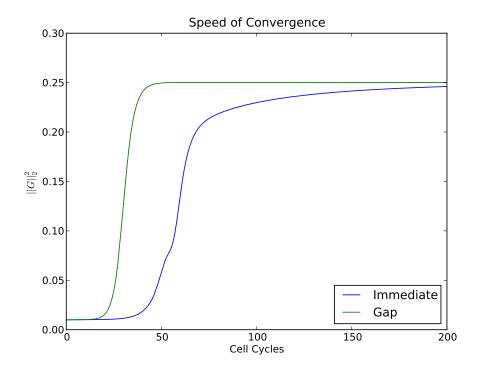
- Conjecture: All area is covered by stable regions.
- There are many regions of Bistability.

# **Another Nice picture**

#### Actual number of clusters:

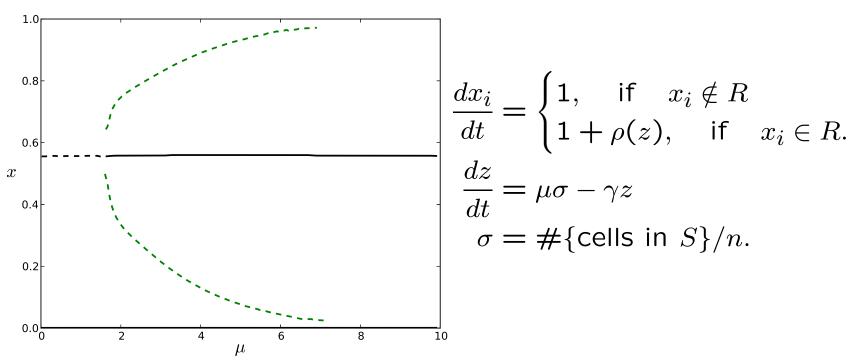


# Model with a gap (delay)



A small delay does not effect the number of clusters. A delay enhances the stability of stable clusters.

## Model with an explicit signaling agent z



2 cluster cyclic solution always exists

- unstable at lower cell density
- it becomes stable via pitchfork
- at high density basin is large.

#### Conclusions for General RS feedback

- Clustering is a robust phenomenon for negative feedback:
  - Not dependent on functional form of feedback.
  - It occurs for large open sets of parameter values.
- Positive feedback tends to produce Synchronization.  $2 \le k \le M$  clusters are only neutrally stable.
- ullet Number of clusters depends heavily on *size* of S and R.
- Clustering is experimentally verified in oscillating cultures.
- The biological mechanism driving Clustering seems to be negative feedback.

#### **Some Open Problems**

- Show that feedback makes the uniform solution unstable.
- Analyze PDE versions of the feedback model, such as:

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left( a(x, [u]) \, u \right) = 0, \quad a(x, [u]) = 1 + f\left( \int_0^1 k(x, y) u(y) \, dy \right),$$

with k(x,y) supported on  $\{x \in R\} \times \{y \in S\}$ , e.g.  $h(x,y) = \chi_{R \times S}$ .

- O. Diekmann and collaborators proved stability of the uniform solution for some cell-cycle PDE models *without* feedback.
- Connect these results with detailed modeling and biology. We are pursuing this in the context of Fruit Fly embryos.

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